

Contents

1	Introduction	1
1.1	Analysis of Image Sets	1
1.2	Thesis Outline	4
1.3	Summary of Contributions	6
2	Low-Dimensional Image Representations and Image Analysis	7
2.1	Image Manifolds	7
2.1.1	Different families of image manifolds	8
2.1.2	Image analysis with manifold models	8
2.1.3	Manifold learning	13
2.1.4	Image representations with parametric dictionaries	14
2.2	Image Analysis	15
2.2.1	Image registration	16
2.2.2	Image classification	19
3	Sampling Parametrizable Manifolds	24
3.1	Fast Manifold Distance Estimation with Sampling	24
3.2	Manifold Discretization for Minimal Distance Estimation Error	25
3.3	Classification-Based Discretization of Multiple Manifolds	27
3.3.1	Classification with discrete samples on manifolds	28
3.3.2	Discretization algorithm	31
3.3.3	Sample budget allocation	33
3.4	Experimental Results	34
3.4.1	Setup	34
3.4.2	Results on registration accuracy	36
3.4.3	Results on transformation-invariant classification	37
3.4.4	Discussion of results	40
3.5	Conclusion	42
4	Learning Pattern Transformation Manifolds	43
4.1	Manifold Learning with Data Priors	43
4.2	Computation of PTMs for Signal Approximation	45
4.2.1	Problem formulation	45

4.2.2	PTM building algorithm	47
4.2.3	Experimental results	51
4.3	Joint Computation of PTMs for Classification	56
4.3.1	Problem formulation	56
4.3.2	Classification-driven PTM learning	57
4.3.3	Implementation details	61
4.3.4	Experimental results	62
4.4	Complexity Analysis	67
4.5	Conclusion	68
5	Analysis of Image Registration with Tangent Distance	69
5.1	Overview of Tangent Distance Analysis	69
5.2	Image Registration with Tangent Distance	71
5.2.1	Notations	72
5.2.2	Tangent distance algorithm	73
5.2.3	Problem formulation	74
5.3	Analysis of Tangent Distance	75
5.3.1	Upper bound for the alignment error	75
5.3.2	Alignment error with low-pass filtering	76
5.4	Experimental Results	85
5.5	Discussion of Results	92
5.6	Conclusion	94
6	Analysis of Image Registration with Descent Methods	95
6.1	Overview of Image Registration Analysis	95
6.2	Analysis of Alignment Regularity	97
6.2.1	Notation and problem formulation	97
6.2.2	Estimation of SIDEN	99
6.2.3	Variation of SIDEN with smoothing	101
6.3	Analysis of Alignment Accuracy in Noisy Settings	103
6.3.1	Derivation of an upper bound on alignment error for Gaussian noise	104
6.3.2	Generalization of the alignment error bound to arbitrary noise models	109
6.3.3	Influence of filtering on alignment error	111
6.4	Experimental Results	113
6.4.1	Evaluation of alignment regularity analysis	113
6.4.2	Evaluation of alignment accuracy analysis	114
6.4.3	Application: Design of an optimal registration algorithm	120
6.5	Discussion of Results	123
6.6	Conclusion	125
7	Conclusions	127

A Appendix	130
A.1 Proof of Proposition 2	130
A.2 Derivation of total squared tangent distance \hat{E}	131
A.3 Computation of the DC Decompositions in Section 4.2.3	132
A.4 Proof of Proposition 3	134
B Appendix	135
B.1 Proof of Theorem 1	135
B.2 Derivations of $\ \partial_i \hat{p}_\lambda\ $ and $\ \partial_{ij} \hat{p}_\lambda\ $ in terms of pattern spatial derivatives	138
B.3 Proof of Lemma 1	140
B.4 Proof of Lemma 2	147
C Appendix	154
C.1 Exact expressions for the parameters in Lemma 3	154
C.2 Exact expressions for the parameters in Lemma 4	155
C.3 Exact expressions for the parameters in Lemma 5	156