



Contents

Acknowledgements	i
Abstract (English/Français)	iii
List of figures	xi
List of tables	xv
Introduction	1
1 Background and Motivation	3
1.1 Background	3
1.2 Applications	4
1.3 Challenges	5
1.4 Generic architecture	6
1.5 Contributions of this thesis	8
2 State of the art	11
2.1 Sensing platforms	11
2.1.1 Dedicated Hardware	11
2.1.2 Smartphones	12
2.2 Sensor abstraction	13
2.2.1 Sensor scheduling	16
2.3 Context inference	18
2.3.1 Activity recognition	19
2.3.2 Location	21
2.3.3 Environment	23
2.3.4 Proximity	25
2.3.5 Health	28
2.4 Sensor fusion	31
3 Collaborative sensing	33
3.1 Introduction	33
3.2 Related Work	35
3.2.1 Centralized coordination	35

3.2.2	Opportunistic collaboration	35
3.2.3	Ad-hoc coordination	36
3.2.4	Fairness	36
3.3	Problem Formulation	37
3.3.1	General definitions	37
3.3.2	Specific instance	38
3.4	Opportunistic Strategy	40
3.4.1	Base-strategy	40
3.4.2	Synchronization	40
3.4.3	Time-window	41
3.4.4	Parameters selection	43
3.5	Theoretical Optimum	43
3.5.1	Definitions	45
3.5.2	Competitive analysis	47
3.6	Evaluation	48
3.6.1	Dataset descriptions	48
3.6.2	Results	51
3.7	Conclusion	55
4	Optimal Sampling	57
4.1	Introduction	57
4.2	Related Work	58
4.2.1	Sensor Placement in WSN	58
4.2.2	Sensing from Mobile Sensors	58
4.2.3	Time series segmentation	59
4.3	Two-Tier Optimal Mobile Sensing	59
4.3.1	Problem Statement	60
4.3.2	Near-Optimal Segmentation	60
4.3.3	Near-Optimal Sampling	63
4.4	Experimental Evaluations	66
4.4.1	Segmentation Results	67
4.4.2	Sampling Results	68
4.4.3	Near-Optimal Combination	71
4.5	Conclusion	71
5	State identification	73
5.1	Introduction	73
5.1.1	Solution overview	75
5.2	Related Work	76
5.2.1	Time series segmentation	76
5.2.2	Online frequent pattern mining	77
5.2.3	Time series subsequences clustering	77
5.2.4	Time series features extraction	78

5.3	State-Preserving Symbolic Representation	79
5.3.1	State Preservation Index	79
5.3.2	The Spclust Algorithm	81
5.3.3	Run Length Encoding	82
5.4	The StateFinder Algorithm	82
5.4.1	Overview	82
5.4.2	Segmentation	83
5.4.3	Clustering	86
5.4.4	Improving segmentation accuracy	87
5.4.5	Reverting States	88
5.5	Applications	89
5.5.1	State Anomaly Detection	89
5.5.2	State Forecasting	90
5.5.3	Data Compression	90
5.6	Experiments	91
5.6.1	State Preservation Index	91
5.6.2	State Recognition	93
5.6.3	State Forecasting	94
5.6.4	State Anomaly Detection	96
5.6.5	Running Time	96
5.7	Conclusion	97
6	Application example: Air pollution exposure estimation for personalized health	99
6.1	Introduction	99
6.2	Related Work	100
6.2.1	Assessing pollution exposure	100
6.2.2	Personal monitoring devices	101
6.3	System architecture	102
6.4	Personal Sensing Device	103
6.4.1	Hardware	103
6.4.2	Software	104
6.5	Aggregation Server	105
6.6	Sensor Fusion	107
6.6.1	Activity and breathing	107
6.6.2	Location	108
6.6.3	Pollution concentration	108
6.6.4	Pollution exposure	109
6.7	Experiments	109
6.7.1	GSN server	109
6.7.2	tinyGSN	110
6.8	Discussion	111

Contents

7 Conclusion	113
7.1 Future directions	114
Bibliography	149
Curriculum Vitae	151